Mid-level Elements for Object Detection

Analysis of Failure Modes

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1. Failure Modes

We use the diagnostic framework from [2] to better understand the failure modes of our system on PASCAL VOC-2007 [1] (See Section 4.2 in main paper). As the Figure 1 shows, in case of person, the localization error is quite significant (the right most curve in Figure 1). One way to combat this kind of error would be to include more spatial information in the feature vector, though naive approach may result in a prohibitively large feature. Note, however, that we don't need to use all visual elements simultaneously (in contrast with other representations); hence, once we have identified a category and merely need to localize it, we might build a more sophisticated feature vector using only the relevant elements. As a future work, we plan to investigate if we can use category-specific mid-level elements to localize better. In case of animals also, both localization and similar-category errors indicate considerable room for improvement.



Figure 1. Diagnostic analysis using [2] to better understand the failure modes of our system.

2. False Positives

In the remaining part of this document, we analyze failure modes for each category using a pie-chart and present qualitative examples highlighting some top false positives for each class.

aeroplane



























Figure 2. Failure Modes for aeroplane.









bicycle

































Figure 3. Failure Modes for bicycle.





bird Cor: 24% H* 9% Loc: 119 Sim: 52%























Figure 4. Failure Modes for bird.









































Figure 5. Failure Modes for boat.



































































Figure 7. Failure Modes for bus.































































































chair Cor: 32% Oth: 28%

Loc: 17























Figure 10. Failure Modes for chair.

















































diningtable



















Figure 12. Failure Modes for diningtable.



















































































Figure 14. Failure Modes for horse.













motorbike







































person



































Figure 16. Failure Modes for person.

pottedplant





































Figure 17. Failure Modes for pottedplant.































Figure 18. Failure Modes for sheep.















































































Figure 20. Failure Modes for train.





tymonitor BG: 28%

th: 12%

Cor: 54%



























Figure 21. Failure Modes for tymonitor.









References

- [1] M. Everingham, L. Van Gool, C. K. I. Williams, J. Winn, and A. Zisserman. The PASCAL Visual Object Classes (VOC) Challenge. *IJCV*, 2010.
- [2] D. Hoiem, Y. Chodpathumwan, and Q. Dai. Diagnosing error in object detectors. In ECCV, 2012.